The CANopen interface can be either top- or bottom-mounted. Both of these options are illustrated below.

# **Top-mounted Interface**



### **Bottom-mounted Interface**



## **CANopen Connector**



Pin	Signal
1, 4, 8	(reserved)
3, 6	CAN GND
2	CAN_L
7	CAN H
5, Housing	CAN_SHLD

#### LED Indicators

LED	Indication	Meaning		
GW Status	See Gateway Installation Sheet			
	Green	Operational state		
	Green (flashing)	Pre-operational state		
RUN	Green (single flash)	Stopped state		
	Red (flashing)	Bus initialization fault		
	Off	Device not powered		
	Red	Bus off		
	Red (single flash)	Warning limit reached		
ERR	Red (double flash)	Error Control Event		
	Red (triple flash)	Sync Error		
	Off	No error		
DW/D	Green	Device powered		
	Off	Device not powered		



#### Baud Rate Switch

A single rotary DIP switch is used to set the baud rate of the interface.

Position	Baud Rate
0	(reserved)
1	10 kbit/s
2	20 kbit/s
3	50 kbit/s
4	125 kbit/s

		Position	Baud Rate		
		5	250 kbit/s		
		6	500 kbit/s		
		7	800 kbit/s		
		8	1 Mbit/s		
		9	(reserved)		

# **Node Address Switches**

Two rotary DIP switches are used to set the node address of the interface between 1 and 99.

Example:

Address = 42  $(4 \times 10) + (2 \times 1)$ 



### **Accessories Checklist**

The following items are required for installation:

- USB cable (included) .
- CANopen configuration tool (not included) .
- . EDS file for CANopen (see www.anybus.com)
- CANopen cable (not included)
- CANopen bus termination resistor<sup>1</sup> (not included)

#### Installation and Startup Summary

- 1. Set the CANopen baud rate and node address
- 2. Attach a termination resistor<sup>1</sup> (optional)
- 3. Connect the gateway to the network
- 4. Connect a PC to the gateway via USB (optional)
- 5. Power up and configure the gateway
- 6. Install the EDS file and configure CANopen (optional)

1 If the node is installed at the end of the bus

#### **Technical Support**

Technical support, documentation and software downloads are available at www.anybus.com.

Technical questions regarding the CANopen fieldbus system should be addressed to CAN in Automation at www.can-cia.de.